

Jeffrey A. Kramer

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<http://mind-melt.com>

Qualifications

- Technical Advisor to Kevin Scott, CTO of Microsoft
- Cofounded of Transparent Financial Systems, raised \$22M in both seed and Series A rounds, as well as hiring from 2 to almost 30 in two years
- Technical Advisor to Paul Allen with oversight and input into 90+ projects and investments
- Successfully designed, built, and deployed a subsea datacenter in about a year
- Designed and built several robotic and autonomous systems, for both commercial and government clients
- Management experience in fintech, military, medical, and private industry research, as well project design and development
- Lead and secondary author in 10 academic, industry, and popular publications, as well as 6 patents (Available on request)
- Master of Science in Computer Science and Bachelor of Science in Electrical Engineering

Specialized Qualifications

- Academic: Mobile Robotics, Computer Vision (3D and 2D), Artificial Intelligence, Machine Learning, Control Systems, Neural Networks, Distributed Systems, Mathematical Filters, Sensor Fusion, Autonomous Vehicles
- Technical: Go, Python, TSDB, SQL, C/C++, Java, Assembler, Ladder, Embedded Systems
- Professional: Technical Management and Leadership, Technical Architecture, Mobile Robotics, Autonomous Vehicles, AR/VR, AI/ML, Remote Sensing, Blockchain, Fintech, Building New Products

Selected Experience**Technical Advisor**

Microsoft

Redmond, WA

June 2022 - Present

- Technical Advisor to Kevin Scott, the CTO of Microsoft
 - Technical and strategic guidance for multiple projects across Microsoft, with a particular focus on engineering systems, AI/ML, and Web3
 - Cross-organizational program management

Cofounder and CTO

Transparent Financial Systems

Seattle, WA

July 2018 - February 2022

- Leadership, Strategy, and Going from 0 to 1
 - Cofounder of Transparent Financial Systems as a spinout of Vulcan Inc. –Transparent is a fintech building software that creates real-time settlement networks
 - Built a team from the ground up from 2 to almost 30 in two years
 - Designed and architected technical and business systems for Xand, Transparent's payment network
 - Raised \$22M for the company from both VCs and large enterprises
 - Accountable for the creation of new cryptographic privacy systems and a highly available distributed system built on a blockchain
 - Led a team of 14 engineers, with three managerial reports

Technical Advisor
Vulcan Inc.

Seattle, WA
Sept. 2017 - Aug. 2018

- Technical Advisor to Paul Allen
 - Technical oversight and review of 90+ projects and investments at Vulcan Inc., as well as the Allen Institutes
 - Problem solving across a broad domain - everything from drones to stop poachers in Africa to satellite systems to halt illegal fishing and from cell science to artificial intelligence
 - Daily interaction with the executive leadership team
 - Ideation and rapid prototyping of hardware and software products, as well as patent creation

Senior Member of Technical Staff
Microsoft Research

Redmond, WA
Aug. 2014 - Sept. 2017

- Engineering and Program Management for Project Natick (<http://projectnatick.com/>)
 - Designed and built a subsea datacenter
 - Solved problems at every level of the stack - from hardware and software to thermal physics models to marketing and promotion
 - Worked with and helped manage a large number of contractors to deliver the project on time
 - Developed and executed rapid experiments to test solutions to difficult problems
 - Proved a variety of alternative cooling schemes for a subsea datacenter
 - Architected and implemented a cloud connected, high speed sensor network for system health and control
 - Successfully troubleshooted difficult problems with the implementation of the vessel in the process of building the system
 - Designed and built the Project Natick website, as well as participated in all aspects of marketing and launch
- Engineering for Holoportation
 - Rebuilt Holoportation (real time AR/VR capture and transmission) to fit into a vehicle
 - Reduced bandwidth requirements by 97%
 - Reduced required onboard computation from seven machines to one
 - Built custom hardware and systems to support in-vehicle Holoportation
- Business Case and System Architecture for Azure Auto prototype
 - Successfully designed and sold through plan to the executive level for what is now Azure Auto
 - Worked with outside automotive companies to serve their needs for connected car and potential future autonomous vehicle solutions

Lead Robotics Engineer

MTD Products

Valley City, OH

Apr. 2013 - Jul. 2014

- Software and Electrical Team Lead on autonomous lawnmower project
 - Led software and electrical product design for autonomous robot system, with five direct reports
 - Worked in a crossfunctional group to design a product using privileged consumer insights
 - Interfaced with stakeholders and suppliers to drive requirements and system choices
 - Built system requirements from focus group and consumer event interactions
 - Designed the software and hardware architecture from the ground up, from embedded systems to the cloud
 - Wrote advanced robot simulation software for test, validation, and analysis
 - Performed sensor system design and analysis

Senior Robotacist

Deeplocal

Pittsburgh, PA

Dec. 2012 - Mar. 2013

- Creative coding and design for multiple clients
 - Designed innovative experiences for major brands
 - Implemented prototypes of experiences
 - Addressed proposals and technology feasibility requests with both advertising agencies and brands
 - Made successful pitches to brands and agencies, including Google

Research Programmer

NREC - National Robotics Engineering Center

Pittsburgh, PA

Oct. 2010 - Dec. 2012

- Research Programmer for multiple robotics projects
 - Hybrid Safety System (HSS) - industrial robot safety system to allow humans and robots to work in close proximity
 - Automated Hauling System (AHS) - autonomous driving for 38 ton mining trucks
 - ACRS - stripping paint from military planes with high powered lasers mounted to giant, mobile robot arms
 - Perception, sensor fusion, and occupancy probability
 - Self-driving vehicles and obstacle detection
 - Testing and verification for sensors and systems

Education**University of South Florida**

Master of Science in Computer Science

Tampa, FL

Aug. 2005 - May 2010

- Thesis: Accurate Localization Given Uncertain Sensors

University of Illinois at Urbana-Champaign

Bachelor of Science in Electrical Engineering

Urbana, IL

Aug. 2000 - May 2004

- Senior Project: Quantum Cryptography Randomization Engine